

## ECE6414: Nonlinear Control Systems Fall 2003; Test#2 CRN: 94870

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Problem 1: State and prove Lyapunov's theorem for autonomous systems. (10 points)Problem 2: State Lasalle's theorem (5 points)Problem 3: State and prove Lyapunov's theorem for nonautonomous systems. You don't have

to prove the asymptotic part. (10 points)

## Problem 4:

(a) Consider

$$\dot{x}_1 = -x_1 + x_2 d(t)$$
$$\dot{x}_2 = -x_1 d(t)$$

Prove that  $Lt_{t\to\infty}x_1(t) = 0$  (10 points) (b) Consider

(b) Consider

$$\dot{x}_1 = x_2$$
  
 $\dot{x}_2 = -h_1(x_1) - h_2(x_2)$ 

$$h_i(0)=0, \quad yh_i(y)>0, \quad \forall y\neq 0, y\in (-a,a)$$

Use  $V(x) = \int_{0}^{x_1} h_1(y) dy + \frac{1}{2} x_2^2$  and show that the origin is asymptotically stable. (10 points)